

Thermal-diffusion and diffusion-thermo effects on MHD three-dimensional axisymmetric flow with Hall and ion-slip currents

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Abstract: This paper investigates the effects of thermal-diffusion and diffusion-thermo on MHD three-dimensional axisymmetric flow of a viscous fluid between radially stretching sheets in the presence of Hall and ion-slip currents, viscous dissipation, Joule heating and first order chemical reaction. Governing partial differential equations are obtained through four laws of conservation, Maxwell's equations and generalized Ohm's law. Obtained partial differential equations are made dimensionless by using similarity transformation. The resulting problems are solved by homotopy analysis method (HAM). Convergence of analytic solutions is ensured. Effects of emerging parameters on dimensionless velocities, temperature and concentration fields are seen through plots. Behavior of different physical parameters on skin friction coefficients, Nusselt number and Sherwood number is analyzed.

[T. Hayat and F. A. Hendi. **Thermal-diffusion and diffusion-thermo effects on MHD three-dimensional axisymmetric flow with Hall and ion-slip currents**] Journal of American Science 2012; 8(1):284-294]. (ISSN: 1545-1003). <http://www.americanscience.org>.

Key words: Soret and Dufour effects, skin friction coefficient, Nusselt number and Sherwood numbers.

1. Introduction

Stretching flows are important type of flows induced by continuously moving boundary and has gained tremendous interest because of their applications in industry and engineering such as aerodynamic extrusion of plastic sheets, cooling of an infinite plate in a cooling bath, liquid film in condensation process, continuous filament extrusion from a dye, the fluid dynamics of a long thread traveling between a feed roll and wind-up roll etc. Crane [1] was first to consider the two-dimensional flow driven by stretching elastic flat sheet which stretches in its own plane with a velocity varying linearly with a distance from a fixed point.

The pioneering work of Crane is subsequently extended by many researchers. Axisymmetric flow driven by radially stretching sheet has been considered by many investigators [3–10].

These studies are restricted to axisymmetric flow induced by a stretching sheet.

Most of the researchers neglected the **Dufour and Soret** effects on heat and mass transfer under the assumption that they are of smaller magnitude than that described by **Fourier's and Fick's** law. Recent advancements show that **Dufour** effect are important in heat transport and **Soret** effects are influential in mass transfer phenomenon. Some recent contributions can be mentioned through refs.[11–14]. In spite of these studied, **Dufour and Soret** effects on MHD three-dimensional axisymmetric flow induced by radially stretching sheets have not yet been studied. The present work is an attempt in this direction. In this paper we

use homotopy analysis method (HAM)[15–29] to solve the nonlinear problem describing MHD axisymmetric flow of a viscous fluid between two radially stretching sheets in the presence of Hall and ion-slip currents, viscous dissipation and Joule heating. In section two, the mathematical formulation and definition of skin friction coefficients, Nusselt number and Sherwood number are presented. Section three extends the application of HAM to construct series solutions of the governing nonlinear problem. Section four analyzes the convergence of HAM solutions. In section five, the results and discussion are given. The conclusions are summarized in section six.

2. Formulation of the problem

Let us consider three dimensional axisymmetric flow of an electrically conducting fluid between two infinite parallel radially stretching sheets placed at $x = \pm L$. The flow is induced by the sheets stretching radially with same rate. The flow is considered symmetric about $x = 0$. A uniform magnetic field B_0 perpendicular to the planes of sheets is applied i.e. in the z-direction. It is assumed that the magnetic Reynolds number is very small and induced magnetic field is neglected. There is no external electric field. Both the sheets have constant temperature T_w and constant concentration C_w . Flow fields are defined by the following expressions

$$V = [u(r, z), v(r, z), w(r, z)], T = T(r, z), C = C(r, z). \quad (1)$$

The relevant governing equations are

$$\frac{\partial u}{\partial r} + \frac{u}{r} + \frac{\partial w}{\partial z} = 0, \tag{2}$$

$$u \frac{\partial u}{\partial r} + w \frac{\partial u}{\partial z} - \frac{v^2}{r} = -\frac{1}{\rho} \frac{\partial p}{\partial r} + \nu \left[2 \frac{\partial^2 u}{\partial r^2} + \frac{\partial^2 u}{\partial z^2} + \frac{\partial^2 w}{\partial r \partial z} + \frac{2}{r} \frac{\partial u}{\partial r} - \frac{\partial u}{r^2} \right] - \frac{\sigma B_0^2}{\rho [(1 + \beta_e \beta_i)^2 + \beta_e^2]} [(1 + \beta_e \beta_i)u - \beta_e v], \tag{3}$$

$$u \frac{\partial v}{\partial r} + w \frac{\partial v}{\partial z} + \frac{vu}{r} = \nu \left[\frac{\partial^2 v}{\partial r^2} + \frac{1}{r} \frac{\partial v}{\partial r} - \frac{v}{r^2} \frac{\partial u}{\partial r} + \frac{\partial^2 v}{\partial z^2} \right] - \frac{\sigma B_0^2}{\rho [(1 + \beta_e \beta_i)^2 + \beta_e^2]} [(1 + \beta_e \beta_i)u - \beta_e v], \tag{4}$$

$$u \frac{\partial w}{\partial r} + w \frac{\partial w}{\partial z} = -\frac{1}{\rho} \frac{\partial p}{\partial z} + \nu \left[2 \frac{\partial^2 w}{\partial z^2} + \frac{\partial^2 w}{\partial r^2} + \frac{1}{r} \frac{\partial w}{\partial r} + \frac{\partial^2 u}{\partial r \partial z} + \frac{\partial^2 w}{r \partial r} \right], \tag{5}$$

$$u \frac{\partial T}{\partial r} + w \frac{\partial T}{\partial z} = \frac{K}{\rho c_p} \left[\frac{\partial^2 T}{\partial r^2} + \frac{1}{r} \frac{\partial T}{\partial r} + \frac{\partial^2 T}{\partial z^2} \right] + \frac{DK_T}{\rho c_p} \left[\frac{\partial^2 C}{\partial r^2} + \frac{1}{r} \frac{\partial C}{\partial r} + \frac{\partial^2 C}{\partial z^2} \right]$$

$$+ \frac{\sigma B_0^2}{\rho c_p [(1 + \beta_e \beta_i)^2 + \beta_e^2]} [u^2 + v^2] + \frac{\mu}{\rho c_p} \left[2 \left(\frac{\partial u}{\partial r} \right)^2 + \left(\frac{\partial v}{\partial r} \right)^2 - \frac{2}{r} v \frac{\partial v}{\partial r} + 2 \frac{\partial u}{\partial z} \frac{\partial w}{\partial r} \right] + \frac{\mu}{\rho c_p} \left[\left(\frac{\partial w}{\partial r} \right)^2 + \frac{v^2}{r^2} + \frac{2}{r^2} u^2 + \left(\frac{\partial u}{\partial z} \right)^2 + \left(\frac{\partial v}{\partial z} \right)^2 + 2 \left(\frac{\partial w}{\partial z} \right)^2 \right], \tag{6}$$

$$u \frac{\partial C}{\partial r} + w \frac{\partial C}{\partial z} = D \left[\frac{\partial^2 C}{\partial r^2} + \frac{1}{r} \frac{\partial C}{\partial r} + \frac{\partial^2 C}{\partial z^2} \right] + \frac{DK_T}{T_m} \left[\frac{\partial^2 T}{\partial r^2} + \frac{1}{r} \frac{\partial T}{\partial r} + \frac{\partial^2 T}{\partial z^2} \right] - K_1 C, \tag{7}$$

where T denotes the temperature field, C the concentration field, σ the density of fluid, σ ($= \frac{e^2 n_e^2 \tau_e}{m_e}$) the electrical conductivity, β_e ($= \frac{w_e \tau_e}{m_e}$) the Hall parameter, β_i ($= \frac{e n_e B_0}{(1 + n_e/n_a) K_{ai}}$) is the ion-slip parameter, τ_e the electron collision time, m_e the mass of electron, w_e the cyclotron frequency, n_e is the electron number density and n_a the neutral particle density, K_{ai} the friction coefficient between ions and neutral particles, K the thermal conductivity, K_T the concentration susceptibility, T_m the mean temperature, K_1 the chemical reaction constant, D the coefficient of mass diffusivity and c_p the specific heat of fluid. The boundary conditions that correspond to the flow under consideration are

$$\frac{\partial u}{\partial z} = 0, v = 0, w = 0, \frac{\partial T}{\partial z} = 0, \frac{\partial C}{\partial z} = 0, \text{ at } z = 0, \tag{8}$$

$$u = ar, v = 0, T = T_w, C = C_w \text{ at } z = L, a > 0.$$

Introducing similarity variables

$$u = r a f'(\eta), v = a r g, w = -2 a L f(\eta), \theta = \frac{T}{T_w}, \phi = \frac{C}{C_w}, \eta = \frac{z}{L}, \tag{9}$$

In Eqs. (2) – (7), one obtains

$$f'''(\eta) - \frac{M^2 Re}{(1 + \beta_e \beta_i)^2 + \beta_e^2} [(1 + \beta_e \beta_i) f'' - \beta_e g'] + 2 Re [f f''(\eta) + g g'] = 0,$$

$$f(0) = 0, f(1) = 0, f'(1) = 1, f''(0) = 0, \tag{10}$$

$$g''(\eta) - \frac{M Re}{(1 + \beta_e \beta_i)^2 + \beta_e^2} [(1 + \beta_e \beta_i) g + \beta_e f'] - 2 Re [f' g - f g'] = 0,$$

$$g(0) = 0, g(1) = 0 \tag{11}$$

$$\theta'' + 2 Re Pr f \theta' + \frac{Pr M Re Ec}{(1 + \beta_e \beta_i)^2 + \beta_e^2} [(f')^2 + (g')^2]$$

$$+ Pr Ec \left[\frac{12}{\delta} (f'')^2 + (f'')^2 + (g'')^2 \right] + Du Pr \phi'' = 0,$$

$$\theta'(0) = 0, \theta(1) = 1 \tag{12}$$

$$\phi'' + 2 Re Sc f \phi' + Sc S_1 \theta'' - Re Sc \gamma \phi = 0,$$

$$\phi'(0) = 0, \phi(1) = 1 \tag{13}$$

Where

$$Re = \frac{a L^2}{\nu}, M = \frac{\sigma B_0^2}{\rho a}, Pr = \frac{\mu c_p}{K}, Du = \frac{DK_T C_w}{\nu C_p T_w},$$

$$Sc = \frac{\nu}{D}, S_1 = \frac{DK_T T_w}{\nu T_m C_w}, Ec = \frac{a^2 r^2}{c_p T_w}, \gamma = \frac{K_1}{a}, \delta = \frac{r^2}{L^2}$$

respectively denote the Reynolds number, Hartman number, Prandtl number, Dufour number, Schmidt number, Soret number, local Eckert number, and first order chemical reaction parameter. Furthermore, $\gamma > 0$ corresponds to generative chemical reaction and $\gamma < 0$ indicates generative chemical reaction.

Definitions of skin friction coefficients C_{fr} and C_{gr} in radial and azimuthal directions,

Nusselt number Nu and Sherwood number Sh are given below

$$C_{fr} = \frac{\tau_{rz}|_{z=0}}{\rho (ar)^2} = \frac{\mu \left(\frac{\partial u}{\partial z} + \frac{\partial w}{\partial r} \right) \Big|_{z=0}}{\rho (ar)^2} = \frac{1}{Re_r} f''(1),$$

$$C_{gr} = \frac{\tau_{\theta z}|_{z=0}}{\rho (ar)^2} = \frac{\mu \frac{\partial v}{\partial z} \Big|_{z=0}}{\rho (ar)^2} = \frac{1}{Re_r} g'(1)$$

$$Nu = -\frac{L q_w}{K T_w} = -\frac{LK \frac{\partial T}{\partial z} \Big|_{z=0}}{K T_w} = -\theta'(1),$$

$$Sh = -\frac{L M_w}{D C_w} = -\frac{LD \frac{\partial C}{\partial z} \Big|_{z=0}}{D C_w} = -\phi'(1), \tag{14}$$

in which $Re_\tau (= \alpha r L / \nu)$ is the local Reynolds number.

3 Solutions by homotopy analysis method

$F(\eta)$, $\theta(\eta)$ and $\phi(\eta)$ in the form of base functions $\{\eta^{2n}, n \geq 0\}$,

can be written as

$$f(\eta) = \sum_{n=0}^{\infty} a_n \eta^{2n+1}, g(\eta) = \sum_{n=0}^{\infty} b_n \eta^{2n+1}$$

$$\theta(\eta) = \sum_{n=0}^{\infty} c_n \eta^{2n}, \phi(\eta) = \sum_{n=0}^{\infty} d_n \eta^{2n}, \quad (16)$$

in which a_n, b_n, c_n and d_n are the coefficients to be determined. The initial guesses $f_0(\eta), g_0(\eta), \theta_0(\eta), \phi_0(\eta)$ and linear operators $\mathcal{L}_i (i = 1 - 3)$ are chosen in the following forms

$$f_0(\eta) = \frac{1}{2} \eta(\eta^2 - 1), g_0(\eta) = 0,$$

$$\theta_0(\eta) = \eta^2, \phi_0(\eta) = \eta^2,$$

$$\mathcal{L}_1[f(\eta)] = \frac{d^4 f}{d\eta^4}, \mathcal{L}_2[g(\eta)] = \frac{d^2 g}{d\eta^2},$$

$$\mathcal{L}_3[\theta(\eta)] = \frac{d^2 \theta}{d\eta^2}, \mathcal{L}_4[\phi(\eta)] = \frac{d^2 \phi}{d\eta^2},$$

whence

$$\mathcal{L}_1[C_1 + C_2 \eta + C_3 \eta^2 + C_4 \eta^3] = 0, \mathcal{L}_1[C_5 + C_6 \eta] = 0,$$

$$\mathcal{L}_2[C_7 + C_8 \eta] = 0, \mathcal{L}_2[C_9 + C_{10} \eta] = 0 \quad (19)$$

and $C_i (i = 1 - 10)$ are the constants.

3.1 Zeroth-order formation problems

The zeroth order deformation problems are constructed as follows

$$(1-q)\mathcal{L}_1[\phi(\eta; q) - f_0(\eta)] = q \hbar_1 N_1[\phi(\eta; q), \Psi(\eta; q)],$$

$$(1-q)\mathcal{L}_2[\psi(\eta; q) - g_0(\eta)] = q \hbar_2 N_2[\psi(\eta; q), \Psi(\eta; q)],$$

$$(1-q)\mathcal{L}_3[\theta(\eta; q) - \theta_0(\eta)] = q \hbar_3 N_3[\theta(\eta; q), \phi(\eta; q), \Psi(\eta; q), \Lambda(\eta; q)],$$

$$(1-q)\mathcal{L}_4[\Lambda(\eta; q) - \phi_0(\eta)] = q \hbar_4 N_4[\Lambda(\eta; q), \theta(\eta; q), \phi(\eta; q), \Psi(\eta; q), (\eta; q)], \quad (20)$$

$$\phi(0; q) = 0, \phi(1; q) = 0, \left. \frac{\partial \phi(\eta; q)}{\partial \eta} \right|_{\eta=1} = 1, \left. \frac{\partial^2 \phi(\eta; q)}{\partial \eta^2} \right|_{\eta=0} = 0,$$

$$\Psi(0; q) = 0, \Psi(1; q) = 0$$

$$\Theta(1; q) = 1, \left. \frac{\partial \Theta(\eta; q)}{\partial \eta} \right|_{\eta=0} = 0,$$

$$\Lambda(1; q) = 1, \left. \frac{\partial \Lambda(\eta; q)}{\partial \eta} \right|_{\eta=0} = c, \quad (21)$$

In above expressions $q \in [0, 1]$ and $\hbar_i \neq 0 (i = 1 - 3)$ are respectively the embedding and auxiliary parameters and

$$\phi(\eta; 0) = f_0(\eta), \Psi(\eta; 0) = g_0(\eta), \Theta(\eta; 0) = \theta_0(\eta), \Lambda(\eta; 0) = \phi_0(\eta)$$

and

$$\phi(\eta; 1) = f(\eta), \Psi(\eta; 1) = g(\eta), \Theta(\eta; 1) = \theta(\eta), \Lambda(\eta; 1) = \phi(\eta).$$

When q varies from 0 to 1, then $\phi(\eta; q)$ varies from the initial guess $f_0(\eta)$ to $f(\eta)$, $g(\eta; q)$ varies from the initial guess $g_0(\eta)$ to $g(\eta)$, $\Theta(\eta; q)$ varies from the initial guess $\theta_0(\eta)$ to $\theta(\eta)$ and $\Lambda(\eta; q)$ varies from the initial guess $\phi_0(\eta)$ to $\phi(\eta)$. The non linear operators $N_{oi} (i = 1 - 4)$ are given below

$$N_1[\phi(\eta; q), \Psi(\eta; q)] = \frac{\partial^4 \phi(\eta; q)}{\partial \eta^4}$$

$$- \frac{M Re}{(1 + \beta_s \beta_i)^2 + \beta_s^2} \left[(1 + \beta_s \beta_i) \frac{\partial^2 \phi(\eta; q)}{\partial \eta^2} - \beta_s \frac{\partial \Psi(\eta; q)}{\partial \eta} \right]$$

$$+ 2 Re \left[\phi(\eta; q) \frac{\partial^2 \phi(\eta; q)}{\partial \eta^2} + \Psi(\eta; q) \frac{\partial \Psi(\eta; q)}{\partial \eta} \right], \quad (22)$$

$$N_2[\psi(\eta; q), \Psi(\eta; q)] = \frac{\partial^2 \psi(\eta; q)}{\partial \eta^2}$$

$$- \frac{M Re}{(1 + \beta_s \beta_i)^2 + \beta_s^2} \left[\beta_s \frac{\partial \psi(\eta; q)}{\partial \eta} + (1 + \beta_s \beta_i) \Psi(\eta; q) \right]$$

$$- 2 Re \left[\psi(\eta; q) \frac{\partial \psi(\eta; q)}{\partial \eta} - \phi(\eta; q) \frac{\partial \Psi(\eta; q)}{\partial \eta} \right], \quad (23)$$

$$N_3[\theta(\eta; q), \phi(\eta; q), \Psi(\eta; q)] = \frac{\partial^2 \theta}{\partial \eta^2} + 2 Re Pr \phi(\eta; q) \frac{\partial \theta(\eta; q)}{\partial \eta}$$

$$+ Pr Ec \left[\frac{12}{\delta} \frac{\partial \phi(\eta; q)}{\partial \eta} + \left(\frac{\partial^2 \phi(\eta; q)}{\partial \eta^2} \right)^2 + \left(\frac{\partial \Psi(\eta; q)}{\partial \eta} \right)^2 \right]$$

$$+ \frac{Pr M Re Ec}{(1 + \beta_s \beta_i)^2 + \beta_s^2} \left[\left(\frac{\partial \phi(\eta; q)}{\partial \eta} \right)^2 + (\Psi(\eta; q))^2 \right]$$

$$+ Du Pr \frac{\partial^2 \Lambda}{\partial \eta^2}, \quad (24)$$

$$N_4[\Lambda(\eta; q), \theta(\eta; q), \phi(\eta; q), \Psi(\eta; q)] = \frac{\partial^2 \Lambda}{\partial \eta^2} + 2 Re Sc \frac{\partial \Lambda(\eta; q)}{\partial \eta} \phi(\eta; q)$$

$$+ Sc Sr \frac{\partial^2 \Theta}{\partial \eta^2} - Re Sc \gamma \Lambda(\eta) \quad (25)$$

Taylor's power series gives

$$\phi(\eta; q) = f_0(\eta) + \sum_{m=1}^{\infty} f_m(\eta) q^m,$$

$$\Psi(\eta; q) = g_0(\eta) + \sum_{m=1}^{\infty} g_m(\eta) q^m,$$

$$\Theta(\eta; q) = \theta_0(\eta) + \sum_{m=1}^{\infty} \theta_m(\eta) q^m,$$

$$\Lambda(\eta; q) = \phi_0(\eta) + \sum_{m=1}^{\infty} \phi_m(\eta) q^m, \quad (26)$$

In which

$$f_m(\eta) = \frac{1}{m!} \left. \frac{\partial^m \Phi(\eta; q)}{\partial \eta^m} \right|_{q=0}, \quad g_m(\eta) = \frac{1}{m!} \left. \frac{\partial^m \Psi(\eta; q)}{\partial \eta^m} \right|_{q=0},$$

$$\theta_m(\eta) = \frac{1}{m!} \left. \frac{\partial^m \Theta(\eta; q)}{\partial \eta^m} \right|_{q=0}, \quad \phi_m(\eta) = \frac{1}{m!} \left. \frac{\partial^m \Lambda(\eta; q)}{\partial \eta^m} \right|_{q=0}, \quad (27)$$

3.2 Higher order deformation problems Writing

$$f_m(\eta) = \{f_0(\eta), f_1(\eta), f_2(\eta), f_3(\eta), \dots, f_m(\eta)\},$$

$$g_m(\eta) = \{g_0(\eta), g_1(\eta), g_2(\eta), g_3(\eta), \dots, g_m(\eta)\},$$

$$\theta_m(\eta) = \{\theta_0(\eta), \theta_1(\eta), \theta_2(\eta), \theta_3(\eta), \dots, \theta_m(\eta)\},$$

$$\phi_m(\eta) = \{\phi_0(\eta), \phi_1(\eta), \phi_2(\eta), \phi_3(\eta), \dots, \phi_m(\eta)\},$$

the so called mth order deformation problems are

$$\mathcal{L}_1[f_m(\eta) - \chi_m f_{m-1}(\eta)] = \hbar_1 \mathcal{R}_{1m}(f_{m-1}(\eta)),$$

$$f_m(0) = 0, f_m(1) = 0, f'_m(1) = 0, f''_m(0) = 0, \quad (29)$$

$$\mathcal{L}_2[g_m(\eta) - \chi_m g_{m-1}(\eta)] = \hbar_2 \mathcal{R}_{2m}(g_{m-1}(\eta)),$$

$$g_m(0) = 0, g_m(1) = 0, \quad (30)$$

$$\mathcal{L}_3[\theta_m(\eta) - \chi_m \theta_{m-1}(\eta)] = \hbar_3 \mathcal{R}_{3m}(\theta_{m-1}(\eta)),$$

$$\theta'_m(0) = 0, \theta_m(1) = 0, \quad (31)$$

$$\mathcal{L}_4[\phi_m(\eta) - \chi_m \phi_{m-1}(\eta)] = \hbar_4 \mathcal{R}_{4m}(\phi_{m-1}(\eta)),$$

$$\phi'_m(0) = 0, \phi_m(1) = 0, \quad (32)$$

$$\chi_m = \begin{cases} 0, & m \leq 1, \\ 1, & m > 1, \end{cases}$$

$$\mathcal{R}_{1m}(f_{m-1}(\eta), g_{m-1}(\eta)) = f''''_{m-1}(\eta)$$

$$- \frac{M Re}{(1 + \beta_e \beta_i)^2 + \beta_e^2} [(1 + \beta_e \beta_i) f'_{m-1}(\eta) - \beta_e g'_{m-1}(\eta)]$$

$$+ 2 Re \sum_{n=0}^{m-1} [f_n(\eta) f''_{m-1-n}(\eta) + g_n(\eta) g'_{m-1-n}(\eta)], \quad (33)$$

$$\mathcal{R}_{2m}(f_{m-1}(\eta), g_{m-1}(\eta)) = f''''_{m-1}(\eta)$$

$$- \frac{M Re \beta_i}{(1 + \beta_e \beta_i)^2 + \beta_e^2} [\beta_e f'_{m-1}(\eta) + (1 + \beta_e \beta_i) g_{m-1}(\eta)]$$

$$- 2 Re \sum_{n=0}^{m-1} [g_n(\eta) f'_{m-1-n}(\eta) + f_n(\eta) g'_{m-1-n}(\eta)], \quad (34)$$

$$\mathcal{R}_{3m}(\theta_{m-1}(\eta), f_{m-1}(\eta), g_{m-1}(\eta), \phi_{m-1}(\eta)) = \theta''''_{m-1}(\eta) + 2 Re Pr \sum_{n=0}^{m-1} f_n(\eta) \theta'_{m-1-n}(\eta)$$

$$+ Pr Ec \sum_{n=0}^{m-1} [f'_n(\eta) f'_{m-1-n}(\eta) + g'_n(\eta) g'_{m-1-n}(\eta) + \frac{12}{\delta} f_n(\eta) f'_{m-1-n}(\eta)]$$

$$+ \frac{M Re}{(1 + \beta_e \beta_i)^2 + \beta_e^2} \sum_{n=0}^{m-1} [f'_n(\eta) f'_{m-1-n}(\eta) + g_n(\eta) g_{m-1-n}(\eta)]$$

$$+ Du Pr \phi''_{m-1}(\eta),$$

$$\mathcal{R}_{4m}(\theta_{m-1}(\eta), f_{m-1}(\eta), g_{m-1}(\eta), \phi_{m-1}(\eta)) = \phi''''_{m-1}(\eta) + Sc Sr \theta''_{m-1}(\eta)$$

$$- Re Sc \gamma \phi''_{m-1}(\eta) + 2 Re Sc \sum_{n=0}^{m-1} f_n(\eta) \phi'_{m-1-n}(\eta). \quad (36)$$

It is found that problems (26) – (28) have the following general solutions

$$f(\eta) = f^*(\eta) + C_1^m + C_2^m \eta + C_3^m \eta^2 + C_4^m \eta^3,$$

$$g(\eta) = g^*(\eta) + C_5^m + C_6^m \eta,$$

$$\theta(\eta) = \theta^*(\eta) + C_7^m + C_8^m \eta,$$

$$\phi(\eta) = \phi^*(\eta) + C_9^m + C_{10}^m \eta, \quad (37)$$

where $f^*(\eta), g^*(\eta), \theta^*(\eta)$ and $\phi^*(\eta)$ are the corresponding particular solutions.

4 Convergence of solutions

The convergence and rate of approximation of series solutions (32)- (35) strongly depend upon the values of auxiliary parameters. For this purpose the \hbar_i – curves are plotted through figures 1 – 3. These figures show that the admissible ranges for \hbar_i are $-1.2 \leq \hbar_1 \leq -0.5$, $-1.1 \leq \hbar_2 \leq -0.7$ and $-1 \leq \hbar_3 \leq -0.3$. However the whole forthcoming calculations are performed when $\hbar_1 = \hbar_2 = \hbar_3 = -1$. In order to ensure the convergence of solutions, Table 1 is constructed. From this table it is evident that the convergence is achieved at 20th order of approximations up to 10th decimal places.

5 Results and Discussion

Figs. 5 – 7 describe the behavior of Hartman number on magnitude of radial velocity $f'(\eta)$, axial velocity $f(\eta)$ and azimuthal velocity $g(\eta)$. These figures show that $f'(\eta)$ and $f(\eta)$ decrease with an increase in M while $g(\eta)$ increases by increasing M . It is noted from Figs. 8 – 10 that an increase in Reynolds number leads to decrease in the magnitude of radial velocity $f'(\eta)$ and axial velocity $f(\eta)$. However azimuthal velocity $g(\eta)$ increases when Reynolds number Re is increased. Figs. 11 and 12 illustrate that the magnitude of radial velocity $f'(\eta)$ and axial velocity $f(\eta)$ increase by increasing Hall parameter β_e whereas azimuthal velocity $g(\eta)$ decreases when Hall parameter is increased (Fig-13). Figs. 14 – 16 demonstrate the influence of ion-slip parameter β_i on magnitude of radial velocity $f'(\eta)$, axial velocity $f(\eta)$ and azimuthal velocity $g(\eta)$. These figures depict that the magnitude of radial velocity $f'(\eta)$ and axial velocity $f(\eta)$ increase whereas azimuthal velocity $g(\eta)$ decreases when ion-slip parameter β_i is increased. Comparison of Figs. 5 – 16 indicates that effects of M and Re are opposite to those of β_e and β_i on the magnitude of radial velocity $f'(\eta)$, axial velocity $f(\eta)$ and azimuthal velocity $g(\eta)$. From Figs. 17 and 18, it is evident that the reverse effect of Pr on dimensionless temperature $\theta(\eta)$ and dimensionless concentration $\phi(\eta)$. The

dimensionless temperature $\theta(\eta)$ increases but dimensionless concentration $\phi(\eta)$ decreases by increasing Schmidt Sc (Figs. 19 – 20). Figs. 21 – 22 reveal that the dimensionless temperature $\theta(\eta)$ and $\phi(\eta)$ show opposite behavior with an increase in Soret number Sr . The dimensionless temperature $\theta(\eta)$ is an increasing function of Du , Re and Ec and $\phi(\eta)$ decreases when Du , Re and Ec are increased as shown in Figs. 23 – 30. Table 2 shows the variation of skin friction coefficients $Re_r C_{fr}$ and $Re_r C_{gr}$ in radial

and azimuthal direction. From this table, it is obvious that skin friction coefficients $Re_r C_{fr}$ and $Re_r C_{gr}$ are an increasing function of Re and M whereas these decrease by decreasing β_e and β_i . Table 3 is prepared for the influence of physical parameters on Nusselt number Nu and Sherwood number Sh . This Table shows that the Nusselt number Nu and Sherwood number Sh are increasing functions of Re , M , Sc , Sr , Pr , Ec and γ and decreasing functions of β_e and β_i .

Table 1. Convergence of HAM solutions for different order of approximations when $Re = M = \beta_e = \beta_i = 2, Sc = Sr = Du = Pr = Ec = \gamma = 0.5, \delta = 12$.

Order of approximations	$f''(1)$	$g'(1)$	$\theta'(1)$	$\phi'(1)$
1	3.504433498	0.06896551724	-1.747126437	0.06666666667
5	3.502994846	0.05721071880	-1.846520547	0.9214152609
8	3.502976934	0.05720645042	-1.849694145	0.9214767184
12	3.502976863	0.05720646969	-1.849691882	0.9215289842
15	3.502976863	0.05720646967	-1.849692097	0.9215288080
20	3.502976863	0.05720646967	-1.849692094	0.9215288131
25	3.502976863	0.05720646967	-1.849692094	0.9215288131

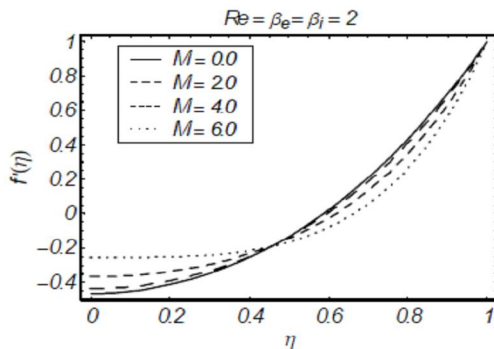


Fig. 5. Influence of M on $f'(\eta)$.

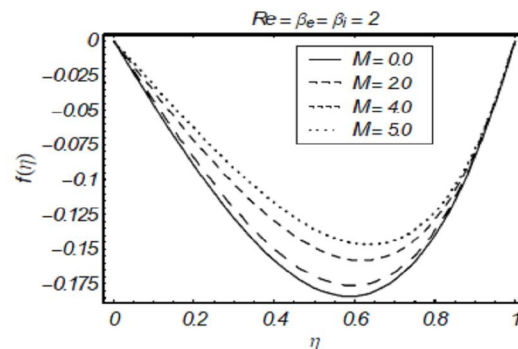


Fig. 6. Influence of M on $f(\eta)$.

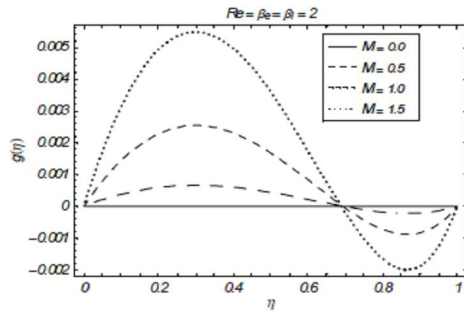


Fig. 7. Influence of M on $g(\eta)$.

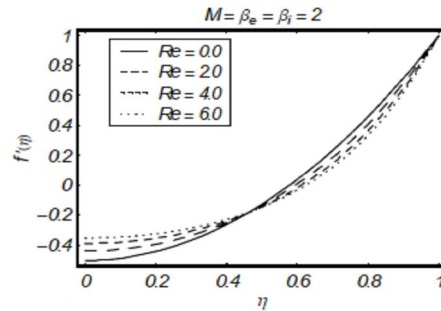


Fig. 8. Influence of Re on $f'(\eta)$.

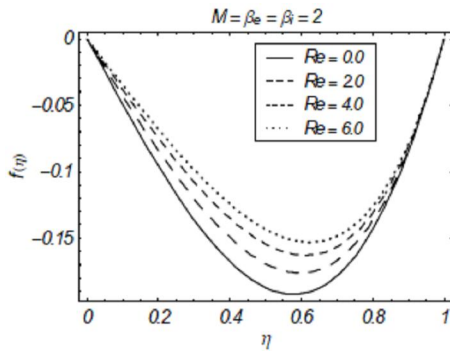


Fig. 9. Influence of Re on $f(\eta)$.

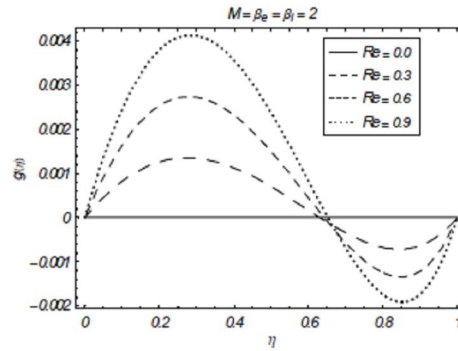


Fig. 10. Influence of Re on $g(\eta)$.

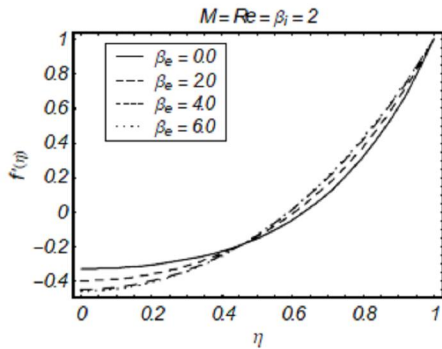


Fig. 11. Influence of β_e on $f'(\eta)$.

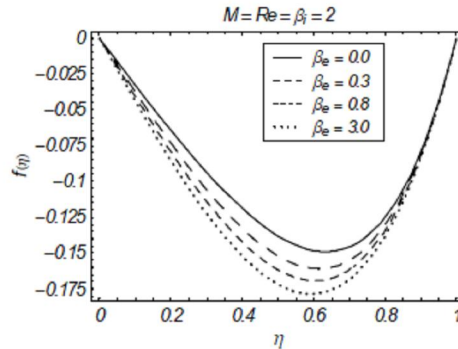


Fig. 12. Influence of β_e on $f(\eta)$.

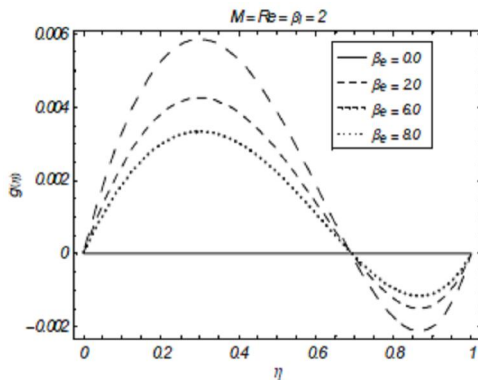


Fig. 13. Influence of β_e on $g(\eta)$.

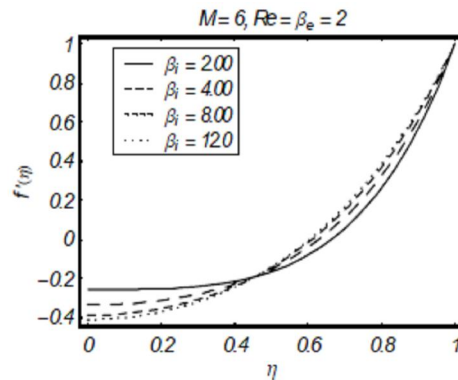


Fig. 14. Influence of β_i on $f'(\eta)$.

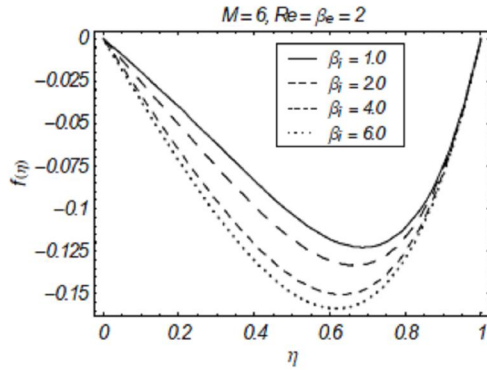


Fig. 15. Influence of β_e on $f(\eta)$.

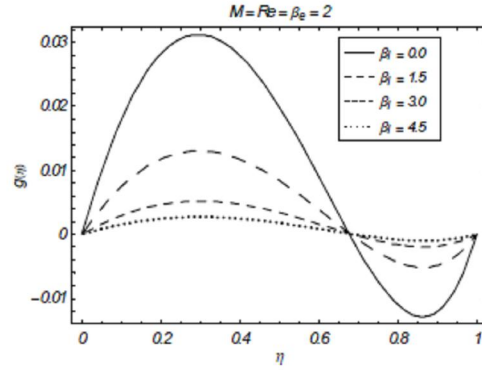


Fig. 16. Influence of β_e on $g(\eta)$.

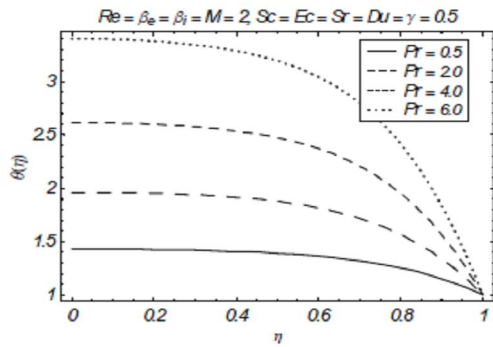


Fig. 17. Influence of Pr on $\theta(\eta)$.

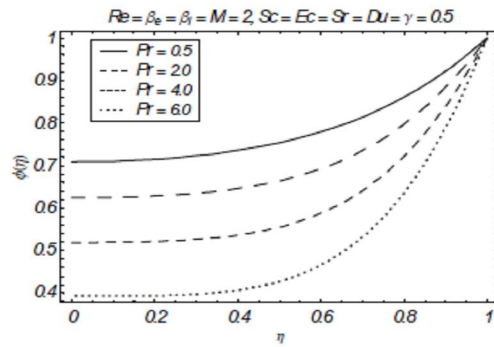


Fig. 18. Influence of Pr on $\phi(\eta)$.

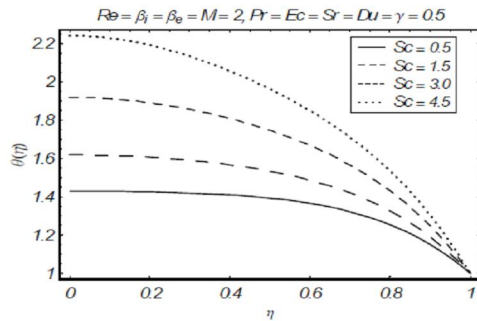


Fig. 19. Influence of Sc on $\theta(\eta)$.

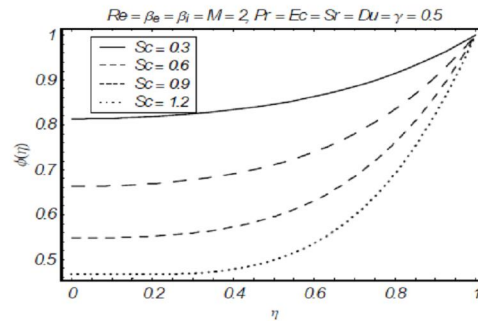


Fig. 20. Influence of Sc on $\phi(\eta)$.

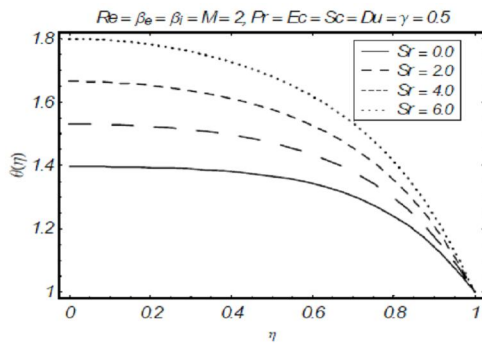


Fig. 21. Influence of Sr on $\theta(\eta)$.

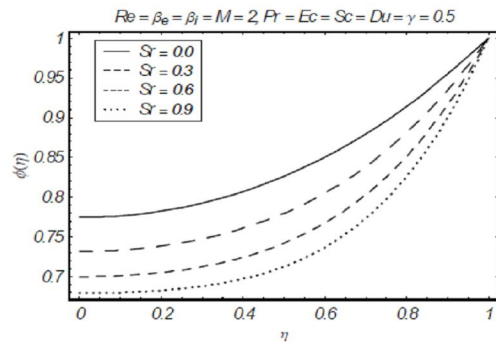


Fig. 22. Influence of Sr on $\phi(\eta)$.

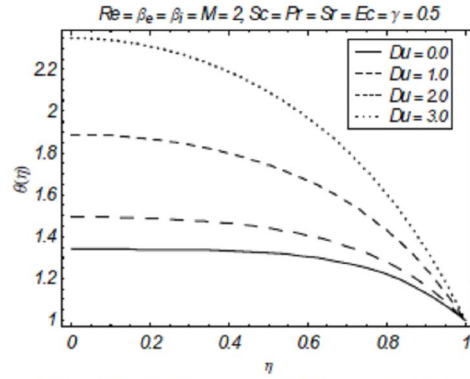


Fig. 23. Influence of Du on $\theta(\eta)$.

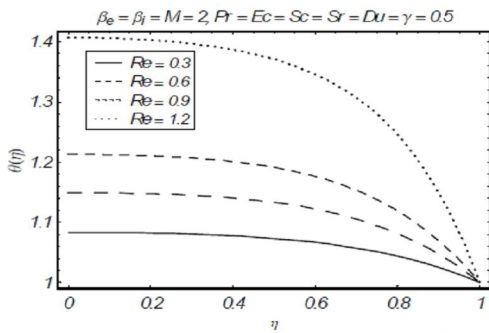


Fig. 25. Influence of Re on $\theta(\eta)$.

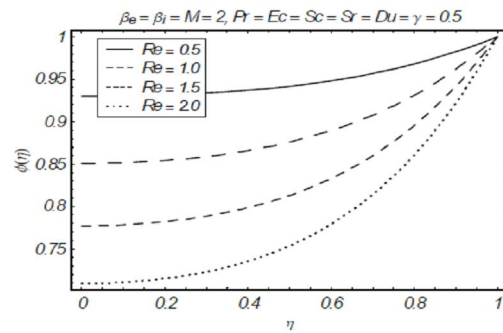


Fig. 26. Influence of Re on $\phi(\eta)$.

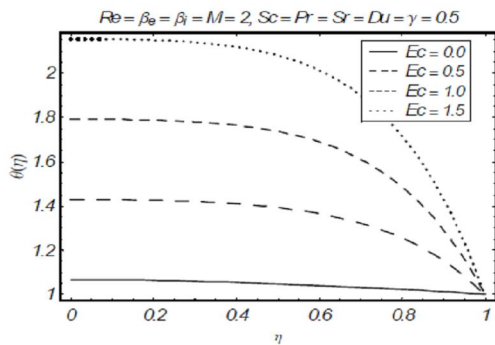


Fig. 27. Influence of Ec on $\theta(\eta)$.

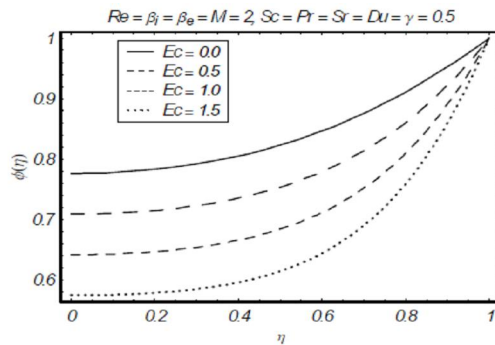


Fig. 28. Influence of Ec on $\phi(\eta)$.

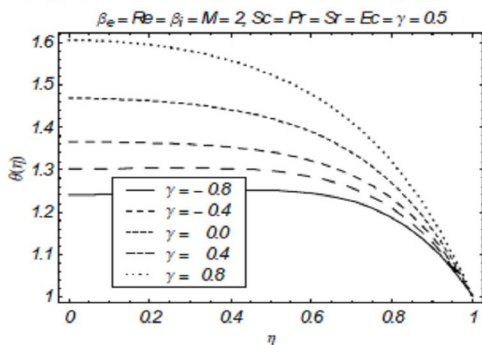


Fig. 29. Influence of γ on $\theta(\eta)$.

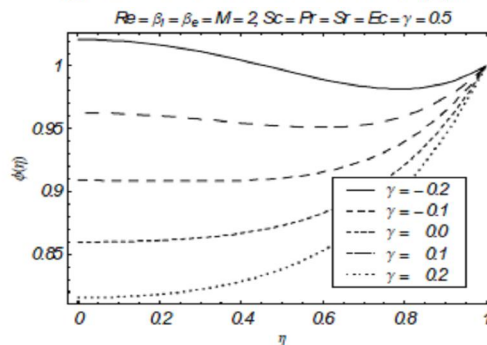


Fig. 30. Influence of γ on $\phi(\eta)$.

Table 2. Variation of skin friction coefficient $C_{f,\gamma}$ for different values of physical parameters.

M	Re	β_i	β_e	$Re_r C_{fr}$	$Re_r C_{gr}$
0.0	2.0	2.0	5.0	3.239833418	0.0000000000
1.0				3.307407692	0.01447375808
2.0				3.502976863	0.05720646967
3.0				3.807821207	0.12548753550
2.0	0.5	2.0	2.0	3.126210064	0.01639036384
	1.5			3.378034991	0.04478752612
	2.5			3.626922424	0.06866388835
	3.5			3.871079696	0.08922423007
2.0	2.0	0.0	2.0	3.572561447	0.3295342724
		1.0		3.590800897	0.1267575429
		2.0		3.502976863	0.05720646967
		3.0		3.442796692	0.03143095076
2.0	2.0	2.0	0.0	4.545163164	0.0000000000
			1.0	3.685601974	0.08176778980
			2.0	3.502976863	0.05720646966
			3.0	3.426056360	0.04312757989

Table 3. Variation of Nusselt number Nu and Sherwood number Sh for different values of emerging parameters.

M	Re	β_i	β_e	Du	Sr	Sc	Pr	Ec	γ	$-Nu$	Sh
0.0	2.0	2.0	2.0	0.5	0.5	0.5	0.5	0.5	0.5	1.833614372	0.9194098210
1.0										1.836739998	0.9196930955
2.0										1.849692094	0.9215288131
3.0										1.880238090	0.9270849609
2.0	0.5	2.0	2.0	0.5	0.5	0.5	0.5	0.5	0.5	0.4435706585	0.2335825756
	1.5									1.368747745	0.6947597913
	2.5									2.342580862	1.145526913
	3.5									3.363687149	1.585348291
2.0	2.0	0.0		0.5	0.5	0.5	0.5	0.5	0.5	1.934273446	0.9415203960
		1.0								1.870809809	0.9260833275
		2.0								1.849692150	0.9215287354
		3.0								1.841874791	0.9200254506
2.0	2.0	2.0	0.0	0.5	0.5	0.5	0.5	0.5	0.5	2.228712593	1.0074908610
			1.0							1.881453411	0.9280871833
			2.0							1.849691882	0.9215289842
			3.0							1.841130301	0.9199550261
2.0	2.0	2.0	2.0	0.0	0.5	0.5	0.5	0.5	0.5	1.599872098	0.8618143193
				1.0						2.136225282	0.9900071202
				2.0						2.856661225	1.162131882
				3.0						3.872516224	1.404726281
2.0	2.0	2.0	2.0	0.5	0.0	0.5	0.5	0.5	0.5	1.734395272	0.4787117831
					1.0					1.981219342	1.427285374
					2.0					2.308670501	2.689229983
					3.0					2.762923533	4.446538062

(Continuation of Table 3)

M	Re	β_i	β_e	Du	Sr	Sc	Pr	Ec	γ	$-Nu$	Sh
2.0	2.0	2.0	2.0	0.5	0.5	0.5	0.5	0.5	0.5	1.849692094	0.9215288131
										2.105039223	1.882504518
										2.364616134	2.879069271
										2.628449674	3.911397123
2.0	2.0	2.0	2.0	0.5	0.5	0.5	0.12	0.5	0.5	0.4066730295	0.5761056816
							0.42			1.524377928	0.8436780815
							0.72			2.812261733	1.151812812
							1.02			4.310743857	1.510122706
2.0	2.0	2.0	2.0	0.5	0.5	0.5	0.5	0.0	0.5	0.1440515805	0.5131098729
								0.5		1.849692094	0.9215288131
								1.0		3.555332607	1.329947753
								1.5		5.260973120	1.738366693
2.0	2.0	2.0	2.0	0.5	0.5	0.5	0.5	0.5	-1.0	1.131386786	1.602056379
									-0.5	1.512496082	0.2729019290
									0.0	1.717201144	0.4487913869
									0.5	1.849692094	0.9215288131
									1.0	1.945443553	1.267388131

6. Final Remark

In this investigation, we have discussed the thermal-diffusion (Soret effect) and diffusion-thermo (Dufour effect) on heat and mass transfer of the steady flow of a viscous fluid between radially stretching sheets in the presence of Hall and ion-slip currents, viscous dissipation and Joule heating. The main point of the present analysis is given below.

- Variation of Re and M on $f'(\eta)$, $f(\eta)$ and $g(\eta)$ is opposite to that of β_e and β_i .
- There are opposite effects of Re , Pr , Sc , Du , Sr , Ec and γ on $\theta(\eta)$ and $\varphi(\eta)$.
- The re is no significant effects β_e and β_i on $\theta(\eta)$ and $\varphi(\eta)$.
- Qualitatively, the effects of Re and M are opposite β_e and β_i on the skin friction coefficients C_{f_r} and C_{g_r} .
- Variation of Re , M , Du , Sc , Sr , Pr , Ec , γ , β_e and β_i on the Nusselt number Nu and Sherwood number Sh are qualitatively similar.

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